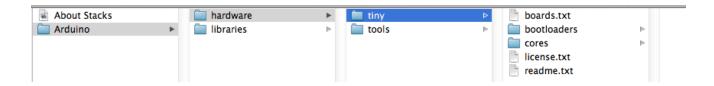
Chipper First Script

Download the up to date version of the Arduino software at the <u>Arduino web page</u> Donwload the board definitions from <u>arduino-tiny</u>

If you are installing the Arduino software on Windows, please see this <u>guide</u> about installing drivers.

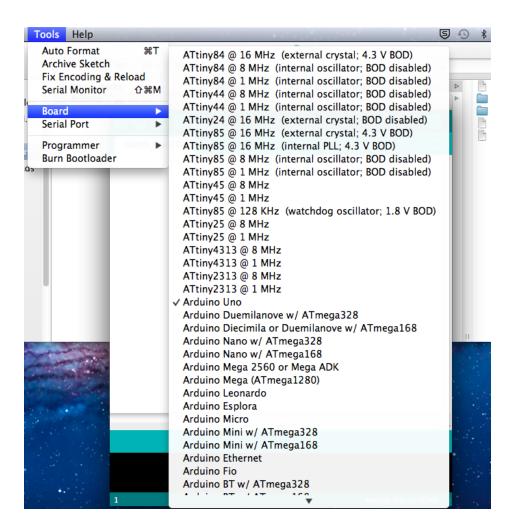
Install the Arduino software. Next we need to install the board definitions for the ATtiny chips. Board definitions are what make the Arduino software compatible with the ATtiny chips.

In your Documents folder, open up the Arduino folder and create a folder called "hardware". Inside of the "hardware" folder take the 2 folders ("tiny" and "tools") inside of the folder, downloaded from attiny-tiny and move them into the "hardware" folder.



Quit the Arduino software and open it again.

Click on the "Tools" tab in the Arduino software and then click on "Board", it should reveal contents that look like this:



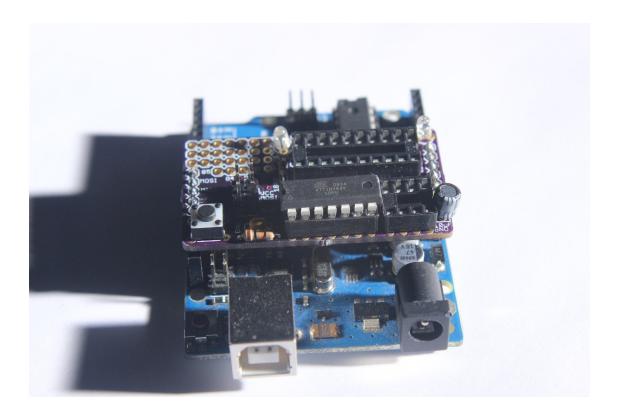
That is everything you need to configure in the Arduino software. At this point, the guide will split if you are programming with an Arduino board or AVR programmer.

Chipper Board Pinouts

Chip	LED(s) Pin	Sensor Pin
ATtiny85	4	5
ATtiny84	0,2	9
ATtiny4313	8,9	14

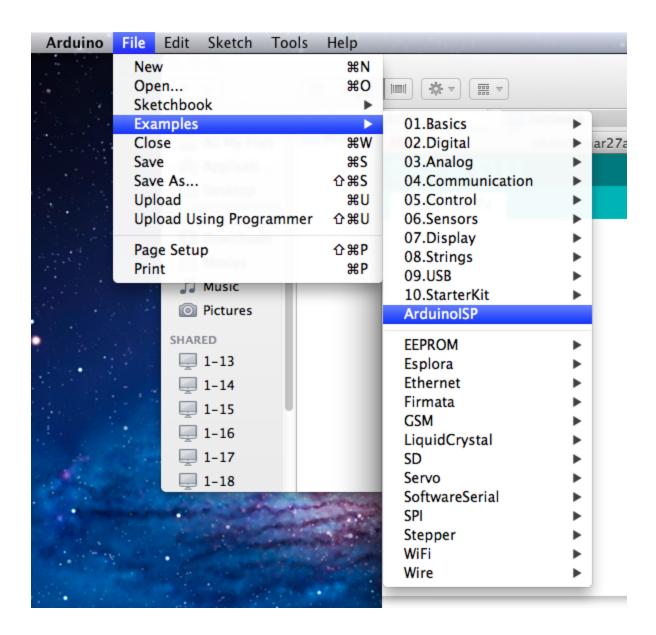
Programming with Arduino Board

If you have an Arduino Uno or previous Uno version (ex. Duemilanove the Leonardo will not work) you can plug the shield directly into the board.



First, however, you need to upload a script to the Arduino Uno.

Open the ArduinoISP sketch and remove anything including the Chipper shield that is attached to the Arduino Uno. Whenever you are programming the Arduino, in order to avoid any upload errors try to remove all peripherals. Remember to select the Arduino Uno under the board section. The majority of uploading issues to the ATtiny chips are caused by selecting the wrong board.



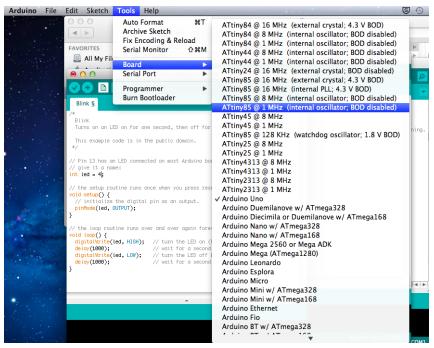
If you are using an Arduino Uno, change the delay at the end of the heartbeat function to 40 ms from 20 ms before uploading. Older boards do not need this change. Before uploading make sure that nothing is plugged into the Arduino. Anytime you want to program an ATtiny with an Arduino, the ArduinoISP sketch has to be on the Arduino.

```
void heartbeat() {
  if (hbval > 192) hbdelta = -hbdelta;
  if (hbval < 32) hbdelta = -hbdelta;
  hbval += hbdelta;
  analogWrite(LED_HB, hbval);
  delay(20);
}</pre>
```

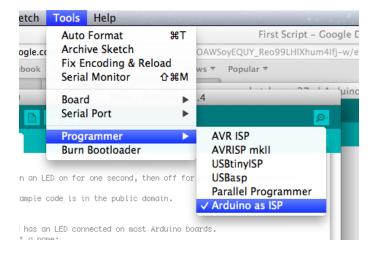
After uploading the script it is time to program the ATtiny. For this example I will be using the ATtiny85.

Plug the ATtiny into the shield. The direction of the chips can be noted by the indent in the body or little hole in ATtiny85 which corresponds to the top of the chip. The top of the chip must always point to the left (the outline of the board on the shield shows a corresponding divot for the ATtiny84 and 2313).

Next, open up the blink sketch from examples>basics>blink. Change the led at the top of the script from 13 to 4. Change the board that you are programming from the Arduino Uno to ATtiny85 1MHz. All of the ATtiny chips are by default set to 1 MHz. We will talk about how to change the clock speed with bootloaders in a few moments.



Then select programmer "Arduino as ISP"



Now you can upload the script. The ATtiny should blink on and off. You will get an error message that looks like this, but do not worry everything is fine:

```
avrdude: please define PAGEL and BS2 signals in the configuration file for part ATtiny85 avrdude: please define PAGEL and BS2 signals in the configuration file for part ATtiny85
```

Using an Arduino Mega

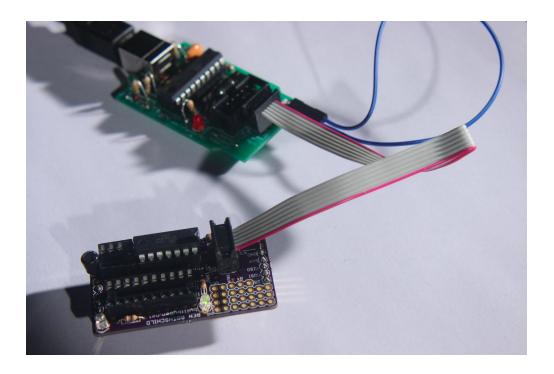
If you are using a board other than an Arduino Uno such as an Arduino Mega you cannot plug the Chipper Shield directly into the Arduino. Instead run jumper wires from MISO,MOSI,RESET,SCK,GND,VCC on the 6 pin header (each pin is labeled) on the Chipper Shield to the appropriate pin on the Arduino board.

For example, at the top of the ArduinoISP sketch it lists the corresponding Arduino Mega pins. Then, while the Arduino has the ArduinoISP sketch on it, upload your program like you would on the Arduino Uno. Select the ATtiny board and change the pin numbers.

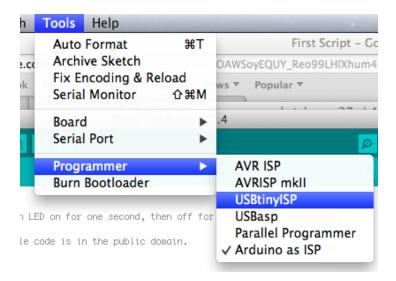
```
// This sketch turns the Arduino into a AVRISP
// using the following arduino pins:
77
// pin name: not-mega:
                                 mega(1280 and 2560)
// slave reset: 10:
                                 53
// MOSI:
               11:
                                 51
// MISO:
              12:
                                 50
// SCK:
              13:
                                 52
```

AVR PROGRAMMER

Here I will be using an <u>USBtinyISP</u>. Plug the 6 pin connector into the 6 pin header on the Chipper Shield so that the ribbon cable is pointing to the left of the Chipper (away from the chips).



Then select USBtinyISP under tools>programmer. Next open up the examples>basics>digital and change the led from 13 to 4. Plug the ATtiny85 into the shield so that the divot on the ATtiny is facing toward the 6 pin connector on the board and upload the script.



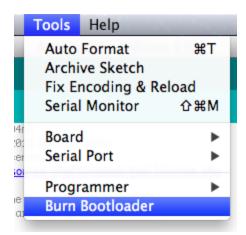
If you get this error message, you can ignore it:

avrdude: please define PAGEL and BS2 signals in the configuration file for part ATtiny85 avrdude: please define PAGEL and BS2 signals in the configuration file for part ATtiny85

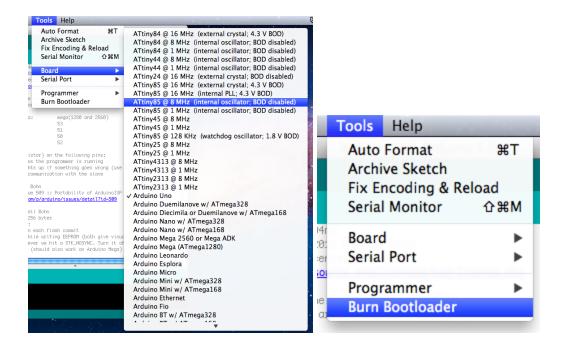
Burning Bootloaders

This can be done either with an Arduino board or an AVR programmer. If you are using an Arduino, configure the Arduino with the ArduinoISP sketch and then select Arduino as ISP as the programmer.

With the AVR programmer plug it into the 6 pins on the Chipper shield and select the appropriate programmer under tools>program. In this case we are using USBtinyISP.



Next, select the board that you wish to configure. In this example we are using an ATtiny85 which by default runs at 1 MHZ. We want to configure it to run on its internal 8MHz clock. You can also run it at 16 MHz with an external clock.



Select ATTiny 8MHz from the list of boards and then select tools>Burn Bootloader. Everything else is taken care of and in a few moments your ATtiny85 will be configured to run at 8MHZ. This is necessary when timing is a crucial part of your program. For example, if you want to run servos off of the ATtiny.

Wondering what pins correspond to what?

Here are the pinouts for the ATtiny85 and 84

